

Efficient Doubling on Genus 3 Curves over Binary Fields

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*Dedicated to my supervisor Prof. Yumin Wang
on occasion of his 70th birthday*

Abstract. The most important and expensive operation in a hyperelliptic curve cryptosystem (HECC) is scalar multiplication by an integer k , i.e., computing an integer k times a divisor D on the Jacobian. Using some recoding algorithms for scalar k , we can reduce a number of divisor class additions during the process of computing scalar multiplication. On the other side, the divisor doublings will stay the same for all kinds of scalar multiplication algorithms. In this paper we accelerate the divisor doublings for genus 3 HECC over binary fields by using special types of curves. Depending on the degree of h , our explicit formulae only require $1I+11M+11S$, $1I+13M+13S$, $1I+20M+12S$ and $1I+26M+11S$ for divisor doublings in the best case, respectively. Especially, for the case of $\deg h = 1$, our explicit formula improve the recent result in [GKP04] significantly by saving $31M$ at the cost of extra $7S$. In addition, we discuss some cases which are not included in [GKP04].

By constructing birational transformation of variables, we derive explicit doubling formulae for special types of equations of the curve. For each type of curve, we analyze how many field operations are needed. So far no attack on any of the all curves suggested in this paper is known, even though some cases are very special. Our results allow to choose curves from a large variety which have extremely fast doubling needing only one third the time of an addition in the best case. Furthermore, an actual implementation of the new formulae on a Pentium-M processor shows their practical relevance.

Keywords: Genus 3 Hyperelliptic Curve, Explicit Doubling Formulae, Fast Arithmetic, Binary Fields

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1 Introduction

In 1988, Neal Koblitz suggested for the first time the generalization of elliptic curves to curves of higher genus for cryptographic use, namely hyperelliptic curves [Kob88,Kob89]. Because of their short operand size compared to other public-key schemes, HECC seem well suitable for small processor architectures, where memory and speed are constrained. During the last decade, elliptic curve cryptosystems (ECC) [Kob87,Mil86] have been extensively studied from both a pure and applied perspective. However, HECC did not obtain a lot of attention until recent years. There has been a major effort in improving the group operations and in implementing HECC on different processors. Using explicit formulae instead of Cantor algorithm has reduced sharply the complexity of arithmetic in the ideal class group of hyperelliptic curves and obtained fast implementation in software [PWGP03,WPW⁺03,Lan03,GMA⁺04,Ava04,Wol04,FWW05] and hardware platform [BCLW02,Cla02,EMY04,KWC⁺04].

For all kinds of cryptographic protocols based on ECC or HECC, the computation of scalar multiplication is the main operation. Scalar multiplication algorithms include usually divisor class additions, doublings and perhaps some precomputations. By some recoding methods for the scalar, we can reduce the number of divisor class additions. However, we cannot decrease the number of divisor class doublings in the general case (for some special curves, it is possible). Therefore, divisor class doublings will become the crucial step, for the performance of the entire cryptosystem. Improving the arithmetic of doubling has a direct impact on the efficiency of the whole system.

In [LS04,BD04], the authors discuss different isogeny classes for genus 2 curves over $GF(2^n)$, n is already the degree of the extension field. They give a complete study of all cases of defining equation of the curve and make a trade-off between speed-up and special parameters. Although we can use Koblitz curves to accelerate the computation of scalar multiplication [GLS00,Lan04], there are only 6 and 24 different isogeny classes for genus 2 and 3 binary curves, respectively. Hence the choice of curves is rather limited. In order to enlarge the range of selecting curves, we will address all kinds of genus 3 curves defined over the extension field in this paper.

For genus 3 curves over $GF(2^n)$, Pelzl et al. [PWGP03] discussed a very special type of curves with $h(x) = 1$ and gave efficient doubling explicit formulae. In [GKP04], the authors proposed efficient algorithms to compute the resultant of two polynomials and of the inverse of one polynomial modulo another, and improved the overall complexity of the addition and doubling algorithms for both even and odd characteristics. Their explicit formulae are applicable to almost all hyperelliptic curves of genus 3. By using a birational transformation of the form $(x, y) \mapsto (\lambda x + \mu, \nu y)$, they discuss five possible types of curves for even characteristic case.

In this article, we generalize the ideas proposed in [LS04] to genus 3 case and improve the results in [GKP04] further. We construct isomorphic transformations first to achieve as many zero coefficients as possible, and then make strong use of the defining equation of the curve to derive explicit doubling formulae.

We discuss some special curves which can lead to fast computation of doubling a divisor class. Finally, we combine the new doubling explicit formulae with the NAF method to compute the scalar multiplication, and give detailed experiment results.

The remainder of the paper is organized as follows: Section 2 states a brief mathematical background related to genus 3 hyperelliptic curves over binary fields. Section 3 describes Harley's algorithm for doubling a divisor class. In section 4, 5, 6, and 7 we derive the new doubling explicit formulae for genus 3 curves according to the different degree of $h(x)$. Section 8 summarizes our contributions. Finally, we present our experimental results in Section 9 and conclude with a discussion of our results in Section 10.

2 Genus 3 Hyperelliptic Curves

In this section we present the representation of the divisor class group elements for genus 3 hyperelliptic curves over characteristic two finite fields. More mathematical background and more details about hyperelliptic curves can be found in the literature [Can87,Kob89,MWZ96,CFA⁺05].

Let $GF(2^n)$ be a binary finite field with 2^n elements. A hyperelliptic curve C of genus 3 over $GF(2^n)$ with one point at infinity is defined by an equation of the form

$$(*) \quad C : Y^2 + h(X)Y = f(X),$$

where $h(X) = h_3X^3 + h_2X^2 + h_1X + h_0 \in GF(2^n)[X]$ is a polynomial of degree ≤ 3 , $f(X) = X^7 + f_6X^6 + f_5X^5 + f_4X^4 + f_3X^3 + f_2X^2 + f_1X + f_0 \in GF(2^n)[X]$ is a monic polynomial of degree 7, and the curve C has no singular point.

The equation (*) defining a hyperelliptic curves C of genus 3 is unique up to a change of coordinates of the form

$$(x, y) \longrightarrow (\alpha^2x + \beta, \alpha^7y + t(x)),$$

Where $\alpha, \beta \in GF(2^n)$ with $\alpha \neq 0$ and $t(x) \in GF(2^n)[x]$ with $\deg t \leq 3$ [Loc94]. Let $P_i = (x_i, y_i) \in \overline{GF(2^n)} \times \overline{GF(2^n)}$ be a point on the curve C and P_∞ be a point at infinity, where $\overline{GF(2^n)}$ is the algebraic closure of $GF(2^n)$. The inverse of $P_i = (x_i, y_i)$ is the point $-P_i = (x_i, y_i + h(x_i))$. P is called a ramification point if $P = -P$ holds. A divisor is a formal sum of points: $D = \sum m_i P_i, m_i \in \mathbb{Z}$. A semi-reduced divisor is given by $D = \sum m_i P_i - (\sum m_i) P_\infty$, where $m_i \geq 0$ and $P_i \neq -P_j$ for $i \neq j$, and semi-reduced divisor D is called reduced if $\sum m_i \leq 3$ holds for genus 3 hyperelliptic curves. The divisor class group $J_C(GF(2^n))$ of C forms a finite abelian group and therefore we can construct cryptosystems based on discrete logarithm problems on the Jacobian of C . Any equivalent class D in $J_C(GF(2^n))$ can be represented by a pair of polynomials (u, v) , which satisfies the following conditions [Mum84]:

$$u(x) = \prod (x + x_i)^{m_i}, v(x_i) = y_i, \deg v < \deg u, u \mid v^2 + hv + f.$$

3 Harley's Algorithm for Divisor Class Doublings

In [GH00], the authors noticed that one can reduce the number of operations by distinguishing between possible cases according to the properties of the input divisors. They proposed an efficient algorithm (Using many computational algebra tricks such as Karatsuba Multiplication, Chinese Remainder Theorem and Newton Iteration) to compute in the Jacobian of hyperelliptic curves. For a complete description about explicit formulae for group operations we refer to [Wol04].

In this paper we concentrate on doublings for genus 3 curves in the most significant case where the input divisor $[u(x), v(x)]$ has full degree and u and h do not have a common factor. Therefore, we assume from now on

$$D = [u(x), v(x)], \quad \deg u(x) = 3, \quad \text{resultant } [u(x), h(x)] \neq 0.$$

Let $u(x) = x^3 + u_2x^2 + u_1x + u_0, v(x) = v_2x^2 + v_1x + v_0$. Using the following Harley algorithm, we can double a divisor class on a Jacobian:

- Step 1. Compute the resultant r of u and h ;
- Step 2. Compute the almost inverse $inv = r/h \bmod u = inv_2x^2 + inv_1x + inv_0$;
- Step 3. Compute $z = ((f - hv - v^2)/u) \bmod u = z_2x^2 + z_1x + z_0$;
- Step 4. Compute $s' = z \cdot inv \bmod u = s'_2x^2 + s'_1x + s'_0$;
- Step 5. Compute $s = (s'/r)$ and make s monic: $s = x^2 + s_1x + s_0$;
- Step 6. Compute $G = s \cdot u = x^5 + g_4x^4 + g_3x^3 + g_2x^2 + g_1x + g_0$;
- Step 7. Compute $u' = u^{-2}\{[G + (r/s_2)v]^2 + (r/s_2)hG + (r/s_2)^2(hv - f)\} = x^4 + u'_3x^3 + u'_2x^2 + u'_1x + u'_0$;
- Step 8. Compute $v' = -[G(s_2/r) + h + v] \bmod u' = v'_3x^3 + v'_2x^2 + v'_1x + v'_0$;
- Step 9. Reduce $u' : u'' = (f - v'h - v'^2)/u' = x^3 + u''_2x^2 + u''_1x + u''_0$;
- Step 10. Compute $v'' = -(v' + h) \bmod u'' = v''_2x^2 + v''_1x + v''_0$.

We now study different cases of equations depending on the degree of h separately because the actual execution of the Harley's algorithm depends on the coefficients of the curve. We will present explicit formulae for four different cases: $\deg h = 0$, $\deg h = 1$, $\deg h = 2$ and $\deg h = 3$. In the two latter cases, we try to find special curves which can lead to a significant speedup. The major speedup is obtained by simplifying and canceling r in the expressions. For hyperelliptic curves of genus 3 and defined over fields of characteristic two there exist no supersingular cases [Gal01,RS02]. I.e. for genus 3 HECC we can take special curves with h constant. Using these special curves, we can obtain explicit formulae with low complexity and better performance regarding the number of required field operations for the execution of the group operations.

4 Case $\deg h = 0$

In this section we assume $\deg h = 0$. One can obtain an isomorphic curve where $f_6 = f_5 = f_4 = f_2 = 0$ and h_0 is divided by any α^7 . To improve the efficiency of HECC, we hope that the coefficient h_0 is 'small' in an isomorphic curve, which allows the multiplication with it to be performed via additions. Hence we

will choose α^7 such that $\frac{h_0}{\alpha^7}$ is 'small' in practical use. If we choose finite fields $GF(2^n)$ with $n \equiv 1 \pmod{3}$ or $n \equiv 2 \pmod{3}$ there are no elements $\alpha \in GF(2^n)$ such that $\alpha^7 = 1$ (the unit element of $GF(2^n)$). Therefore, there is always an α such that $\alpha^7 = h_0$. For $n \equiv 0 \pmod{3}$ this happens with probability $1/7$. We obtain the isomorphic curve by using the following birational transformation of variables and dividing the equation by α^{14} :

$$Y \leftarrow \alpha^7 \tilde{Y} + a \tilde{X}^3 + b \tilde{X}^2 + c \tilde{X}, X \leftarrow \alpha^2 \tilde{X} + d$$

where $d = \sqrt{f_5}$, $a = \alpha^6 \sqrt{f_6 + d}$, $b = \alpha^4 \sqrt{f_4 + f_5 \cdot d + f_6 \cdot d^2 + d^3}$ and $c = \alpha^2 \sqrt{f_2 + f_3 \cdot d + f_6 \cdot d^4 + d^5 + h_0 \cdot b}$. Therefore we obtain a curve of the form $Y^2 + h_0 Y = X^7 + f_3 X^3 + f_1 X + f_0$, usually with $h_0 = 1$. Adding a constant term to the substitution of \tilde{Y} one can achieve $f_0 = 0$ with probability $1/2$. Hence, there are only two parameters f_3, f_1 as opposed to five in the general case showing that the type is indeed special.

With the new curve coefficients the expression r and s will simplify to:

$$r = h_0^3, s_2' = h_0^2 z_2, s_1' = h_0^2 z_1, s_0' = h_0^2 z_0.$$

We note that

$$\begin{aligned} u_3' &= 0, u_2' = s_1'^2 = (s_1'/s_2')^2 = (z_1/z_2)^2, \\ u_1' &= (r/s_2')^2 = h_0^2 (z_2^{-1})^2, u_0' = s_0'^2 = (s_0'/s_2')^2 = (z_0/z_2)^2, \end{aligned}$$

and

$$\begin{aligned} v_3' &= (u_2' + g_3)(s_2'/r) = h_0^{-1}(u_2' z_2 + z_0 + u_2 z_1 + u_1 z_2), \\ v_2' &= (g_4 u_2' + u_1' + g_2)(s_2'/r) + v_2 = h_0^{-1}[(u_2 z_2 + z_1)u_2' + u_1' z_2 + u_2 z_0 + u_1 z_1 + u_0 z_2] + v_2, \\ v_1' &= (g_4 u_1' + u_0' + g_1)(s_2'/r) + v_1 = h_0^{-1}[(u_2 z_2 + z_1)u_1' + u_0' z_2 + u_1 z_0 + u_0 z_1] + v_1, \\ v_0' &= (g_4 u_0' + g_0)(s_2'/r) + h_0 + v_0 = h_0^{-1}[(u_2 z_2 + z_1)u_0' + u_0 z_0] + h_0 + v_0. \end{aligned}$$

Since $f + hv + v^2 = uz + u^2x$ we also have that

$$\begin{aligned} f_0 + h_0 v_0 + v_0^2 &= u_0 z_0, \\ f_1 + h_0 v_1 &= u_1 z_0 + u_0 z_1 + u_0^2, \\ h_0 v_2 + v_1^2 &= u_2 z_0 + u_1 z_1 + u_0 z_2, \\ f_3 &= z_0 + u_2 z_1 + u_1 z_2 + u_1^2, \\ v_2^2 &= z_1 + u_2 z_2, \\ 0 &= u_2^2 + z_2. \end{aligned}$$

Using the equations above, we can calculate cheaply u_2', u_0' and v_3', v_2', v_1', v_0' as follows:

$$\begin{aligned} u_2' &= (z_1/z_2)^2 = [(v_2^2 + u_2 z_2)/z_2]^2 = (v_2^2 z_2^{-1})^2 + u_2^2, \\ u_0' &= (z_0/z_2)^2 = [(f_3 + u_1^2 + u_2 z_1 + u_1 z_2)/z_2]^2 = [(f_3 + u_1^2)z_2^{-1}]^2 + u_1^2 + u_2^2 u_2', \end{aligned}$$

$$\begin{aligned}
v'_3 &= h_0^{-1}(u'_2 z_2 + f_3 + u_1^2), \\
v'_2 &= h_0^{-1}(v_2^2 u'_2 + v_1^2) + h_0 z_2^{-1}, \\
v'_1 &= h_0^{-1}[(v_2^2 + z_2)(u'_1 + u'_0) + v_2^2 u'_0 + f_1 + u_0^2] + h_0 z_2^{-1}, \\
v'_0 &= h_0^{-1}(v_2^2 u'_0 + f_0 + v_0^2) + h_0.
\end{aligned}$$

We give the doubling formulae for this case in Table 1. The operations are counted for the case $h_0 = 1$, h_0^{-1} is 'small' (multiplication with h_0^{-1} are not counted), and arbitrary h_0 . Both h_0^2 and h_0^{-1} are precomputed.

Table 1. Doubling deg $h = 0$, deg $u = 3$

Input	$[u, v], u = x^3 + u_2 x^2 + u_1 x + u_0, v = v_2 x^2 + v_1 x + v_0; h_0^2, h_0^{-1}$			
Output	$[u'', v''] = 2[u, v]$			
Step	Expression	$h_0 = 1$	h_0^{-1} small	h_0 arbitrary
1	Compute $\tilde{u} = u^2$ and $\tilde{v} = v^2$: If $u_2 = 0$ then call the Cantor algorithm $\tilde{u}_2 = u_2^2, \tilde{u}_1 = u_1^2, \tilde{u}_0 = u_0^2, \tilde{v}_2 = v_2^2, \tilde{v}_1 = v_1^2, \tilde{v}_0 = v_0^2$;	6S	6S	6S
2	Compute $u' = x^4 + u_3 x^3 + u_2 x^2 + u_1 x + u_0$: $t_1 = f_3 + \tilde{u}_1, t_2 = f_1 + \tilde{u}_0, t_3 = f_0 + \tilde{v}_0$; $invz_2 = \tilde{u}_2^{-1}, u'_3 = 0, u'_2 = (\tilde{v}_2 invz_2)^2 + \tilde{u}_2$; $u'_1 = h_0^2 (invz_2)^2, u'_0 = (t_1 invz_2)^2 + \tilde{u}_1 + \tilde{u}_2 u'_2$;	1I, 3M, 3S	1I, 4M, 3S	1I, 4M, 3S
3	Compute $v' = v_3 x^3 + v_2 x^2 + v_1 x + v_0$: $v'_3 = h_0^{-1}(u'_2 \tilde{u}_2 + t_1), v'_2 = h_0^{-1}(\tilde{v}_2 u'_2 + \tilde{v}_1) + h_0 invz_2$; $v'_1 = h_0^{-1}[(\tilde{v}_2 + \tilde{u}_2)(u'_1 + u'_0) + \tilde{v}_2 u'_0 + t_2] + h_0 invz_2$; $v'_0 = h_0^{-1}(\tilde{v}_2 u'_0 + t_3)$;	4M	5M	9M
4	Reduce u' , i.e. $u'' = x^3 + u''_2 x^2 + u''_1 x + u''_0$: $u''_2 = v'_3, u''_1 = u'_2, u''_0 = u'_2 u'_2 + v'^2_2 + u'_1$;	1M, 2S	1M, 2S	1M, 2S
5	Compute $v'' = v_2 x^2 + v_1 x + v_0$: $v''_2 = v'_2 + v'_3 u''_2, v''_1 = v'_1 + v'_3 u''_1, v''_0 = v'_0 + v'_3 u''_0$;	3M	3M	3M
Sum		1I, 11M, 11S	1I, 13M, 11S	1I, 17M, 11S

Remark 1. For the case of $h_0 = 1$, we obtain the same explicit formula as in [GKP04] (only saves several field additions).

5 Case deg $h = 1$

In this section we discuss the case of deg $h = 1$. One can obtain an isomorphic curve where $f_6 = f_4 = h_0 = 0$ and h_1 is divided by any α^5 . We will choose α^5 such that $\frac{h_1}{\alpha^5}$ is 'small' in practical use. If we choose finite fields $GF(2^n)$ with n not being divided by 4 there are no elements $\alpha \in GF(2^n)$ such that $\alpha^5 = 1$. Therefore, there is always an α such that $\alpha^5 = h_0$. For $n \equiv 0 \pmod{4}$ this happens with probability $1/5$. We obtain the isomorphic curve by using the

following birational transformation of variables and dividing the equation by α^{14} :

$$Y \leftarrow \alpha^7 \tilde{Y} + s \tilde{X}^3 + t \tilde{X}^2, X \leftarrow \alpha^2 \tilde{X} + \beta$$

Where $\beta = \frac{h_0}{h_1}$, $s = \alpha^6 \sqrt{f_6 + \beta}$ and $t = \alpha^4 \sqrt{f_4 + f_5 \beta + f_6 \beta^2 + \beta^3 + h_1 \sqrt{f_6 + \beta}}$. Hence, we obtain a curve of the form $Y^2 + h_1 XY = X^7 + f_5 X^5 + f_3 X^3 + f_2 X^2 + f_1 X + f_0$, usually with $h_1 = 1$. Adding a linear factor to the substitution of \tilde{Y} one can achieve $f_2 = 0$ with probability 1/2. A constant term leads to $f_1 = 0$. Therefore, there are only three free parameters f_5, f_3, f_0 .

With the new curve coefficients the expression r and s will simplify to:

$$\begin{aligned} r &= u_0 h_1^3, s'_2 = z_0 h_1^2, s'_1 = (u_2 z_0 + u_0 z_2) h_1^2, s'_0 = (u_1 z_0 + u_0 z_1) h_1^2, \\ r s'_2 &= u_0 z_0 h_1^5, s_2 = \frac{s'_2}{r} = \frac{z_0}{u_0 h_1}. \end{aligned}$$

In this case, we have that

$$u'_3 = 0, u'_2 = s_1^2 = (s'_1/s'_2)^2 = (u_2 + u_0 \cdot \frac{z_2}{z_0})^2,$$

$$u'_1 = (r/s'_2)^2 = h_0^2 u_0^2 (z_0^{-1})^2, u'_0 = s_0^2 = (s'_0/s'_2)^2 = (u_1 + u_0 \cdot \frac{z_1}{z_0})^2,$$

and

$$v'_3 = (u'_2 + g_3)(s'_2/r) = h_1^{-1} [z_2 \cdot (u_0 \cdot \frac{z_2}{z_0}) + z_1 + u_2 z_2],$$

$$v'_2 = (g_4 u'_2 + u'_1 + g_2)(s'_2/r) + v_2 = h_1^{-1} [z_2 u'_2 + \frac{h_1}{s_2} + u_2 z_1 + u_1 z_2 + z_0] + v_2,$$

$$v'_1 = (g_4 u'_1 + u'_0 + g_1)(s'_2/r) + h_1 + v_1 = h_1^{-1} [\frac{1}{h_1 s_2} (\frac{z_2 h_1}{s_2} + z_1^2) + u_2 z_0 + u_1 z_1 + u_0 z_2] + v_1,$$

$$v'_0 = (g_4 u'_0 + g_0)(s'_2/r) + v_0 = h_1^{-1} (z_2 u'_0 + u_1 z_0 + u_0 z_1) + v_0.$$

Since $f + hv + v^2 = uz + u^2x$ we also obtain that

$$f_0 + v_0^2 = u_0 z_0 \quad (= r s'_2 / h_1^5),$$

$$f_1 + h_1 v_0 = u_1 z_0 + u_0 z_1 + u_0^2,$$

$$f_2 + h_1 v_1 + v_1^2 = u_2 z_0 + u_1 z_1 + u_0 z_2,$$

$$f_3 + h_1 v_2 = z_0 + u_2 z_1 + u_1 z_2 + u_1^2,$$

$$v_2^2 = z_1 + u_2 z_2,$$

$$f_5 = u_2^2 + z_2.$$

Using the equations above, we can calculate cheaply u'_2, u'_0 and v'_3, v'_2, v'_1, v'_0 as follows:

$$u'_2 = (u_2 + u_0 \cdot \frac{z_2}{z_0})^2 = (u_2 + u_0 \cdot \frac{z_2}{u_0 h_1 s_2})^2 = (u_2 + \frac{z_2}{h_1 s_2})^2,$$

$$\begin{aligned}
u'_0 &= (u_1 + u_0 \cdot \frac{z_1}{z_0})^2 = (u_1 + u_0 \cdot \frac{z_1}{u_0 h_1 s_2})^2 = (u_1 + \frac{z_1}{h_1 s_2})^2, \\
v'_3 &= h_1^{-1}(\frac{z_2^2}{h_1 s_2} + v_2^2), \\
v'_2 &= h_1^{-1}(z_2 u'_2 + \frac{h_1}{s_2} + f_3 + u_1^2), \\
v'_1 &= h_1^{-1}[\frac{1}{h_1 s_2}(z_2 \cdot \frac{h_1}{s_2} + z_1^2) + f_2 + v_1^2], \\
v'_0 &= h_1^{-1}(z_2 u'_0 + f_1 + u_0^2).
\end{aligned}$$

We note that $f_0 + v_0^2 = u_0 \cdot z_0 = r \cdot s_2'/h_1^5$, so it is very cheap to calculate rs_2' as the exact coefficients of z are not necessary. In Table 2, we present the doubling formula for this case. The operations are counted for the case $h_1 = 1, h_1^{-1}$ is 'small' (multiplication with h_1^{-1} are not counted), and arbitrary h_1 . Both h_1^2 and h_1^{-1} are precomputed. In Step 2 the inversion and multiplication with k_0 can also be replaced by a division as the inverse is not used later on.

Table 2. Doubling deg $h = 1$, deg $u = 3$

Input	$[u, v], u = x^3 + u_2 x^2 + u_1 x + u_0, v = v_2 x^2 + v_1 x + v_0; h_1^2, h_1^{-1}$			
Output	$[u'', v''] = 2[u, v]$			
Step	Expression	$h_1 = 1$	h_1^{-1} small	h_1 arbitrary
1	Compute rs_2' : $k_0 = u_0^2, z_2 = f_5 + u_2^2, t_1 = v_2^2$; $z_1 = t_1 + u_2 z_2, w_0 = f_0 + v_0^2 (= rs_2'/h_1^5)$; If $w_0 = 0$ then call the Cantor algorithm	1M, 4S	1M, 4S	1M, 4S
2	Compute $1/h_1 s_2$ and s_1, s_0 : $w_1 = (1/w_0) \cdot k_0 (= 1/h_1 s_2), k_1 = z_2 w_1$; $k_2 = z_1 w_1, s_1 = u_2 + k_1, s_0 = u_1 + k_2$;	1I, 3M	1I, 3M	1I, 3M
3	Compute $u' = x^4 + u_3' x^3 + u_2' x^2 + u_1' x + u_0'$: $w_2 = h_1^2 w_1 (= h_1/s_2), u_3' = 0$; $u_2' = s_1^2, u_1' = w_2 w_1, u_0' = w_2 + s_0^2$;	3S	2M, 2S	2M, 2S
4	Compute $v' = v_3' x^3 + v_2' x^2 + v_1' x + v_0'$: $v_3' = h_1^{-1}(z_2 k_1 + t_1), v_2' = h_1^{-1}(z_2 u_2' + w_2 + f_3 + u_1^2)$; $v_1' = h_1^{-1}[w_1(z_2 w_2 + z_1^2) + f_2 + v_1^2]$; $v_0' = h_1^{-1}(z_2 u_0' + f_1 + u_0^2)$;	5M, 4S	5M, 4S	9M, 4S
5	Reduce u' , i.e. $u'' = x^3 + u_2'' x^2 + u_1'' x + u_0''$: $u_2'' = v_3', u_1'' = f_5 + u_2'$; $u_0'' = f_4 + u_2' u_2' + v_2'^2 + u_1' + h_1 v_3'$;	1M, 2S	2M, 2S	2M, 2S
6	Compute $v'' = v_2'' x^2 + v_1'' x + v_0''$: $v_2'' = v_2' + v_3' u_2', v_1'' = v_1' + v_3' u_1' + h_1, v_0'' = v_0' + v_3' u_0'$;	3M	3M	3M
Sum		1I, 13M, 13S	1I, 16M, 12S	1I, 20M, 12S

Remark 2. The algorithm in [GKP04] needs $1I, 44M, 6S$ to compute divisor class doubling. However, our derived explicit formula requires only $1I, 13M, 13S$ in this case. Compared with the explicit formula in [GKP04], our formula save $31M$ at the cost of extra $7S$.

6 Case deg $h = 2$

If h is of degree two then we cannot make any of its coefficients zero in general. In this section we will discuss special curves with $h_1 = 0$, that is, the curves having the form $Y^2 + (h_2X^2 + h_0)Y = X^7 + f_6X^6 + f_5X^5 + f_4X^4 + f_3X^3 + f_2X^2 + f_1X + f_0$, which allows for a significant speedup. By making a change of coordinates we can obtain $f_5 = f_3 = f_2 = h_0 = 0$ and h_2 is divided by any α^3 . We will choose α^3 such that $\frac{h_2}{\alpha^3}$ is 'small' in practical use. If, as usual, one choose finite $GF(2^n)$ with n odd there are no non-trivial cube roots of unity. Hence, there is always an α such that $\alpha^3 = h_2$. For even n this happens with probability $1/3$. The isomorphic curve is obtained by using the following birational transformation of variables and dividing the equation by α^{14} :

$$Y \leftarrow \alpha^7 \tilde{Y} + m \tilde{X}^3 + s \tilde{X} + t, X \leftarrow \alpha^2 \tilde{X} + \beta$$

where $\beta = \sqrt{\frac{h_0}{h_2}}$, $m = \alpha^6 \cdot \frac{f_5 + \beta^2}{h_2}$, $s = \alpha^2 \cdot \frac{f_3 + \beta^4}{h_2}$ and $t = \frac{h_2^2(f_2 + f_3\beta + f_6\beta^4 + \beta^5) + f_3^2 + \beta^8}{h_2^3}$. Hence, we obtain a curve of the form $Y^2 + h_2X^2Y = X^7 + f_6X^6 + f_4X^4 + f_1X + f_0$, usually with $h_2 = 1$. Adding a quadratic factor to the substitution of \tilde{Y} one can achieve $f_4 = 0$ with probability $1/2$. Accordingly, there are only three free parameters f_6, f_1, f_0 .

Then the expressions for r and s will simplify to:

$$\begin{aligned} r &= u_0^2 h_2^3, s'_2 = (u_1 z_0 + u_0 z_1) h_2^2, s'_1 = [u_2(u_1 z_0 + u_0 z_1) + u_0 z_0] h_2^2, \\ s'_0 &= [u_1(u_1 z_0 + u_0 z_1) + u_0(u_2 z_0 + u_0 z_2)] h_2^2, \\ s_1 &= \frac{s'_1}{s'_2} = u_2 + k_1, s_0 = \frac{s'_0}{s'_2} = u_1 + k_2, \end{aligned}$$

where $k_1 = \frac{u_0 z_0}{u_1 z_0 + u_0 z_1}$ and $k_2 = \frac{u_0(u_2 z_0 + u_0 z_2)}{u_1 z_0 + u_0 z_1}$. In this case, we have that

$$\begin{aligned} u'_3 &= 0, u'_2 = s_1^2, u'_1 = \frac{r}{s_2} \left(h_2 + \frac{r}{s_2} \right) = h_2^2 w_1 (1 + w_1), \\ u'_0 &= \frac{r}{s_2} \left[h_2 (u_2 + s_1) + \frac{r f_6}{s_2} \right] + s_0^2 = h_2^2 w_1 (k_1 + f_6 w_1) + s_0^2, \end{aligned}$$

where $w_1 = \frac{u_0^2}{u_1 z_0 + u_0 z_1}$ and

$$v'_3 = (u'_2 + g_3)(s'_2/r) = h_2^{-1} \left[z_2 + \frac{(u_0 z_0)^2}{u_0^2 (u_1 z_0 + u_0 z_1)} \right],$$

$$\begin{aligned} v'_2 &= (g_4 u'_2 + u'_1 + g_2)(s'_2/r) + h_2 + v_2 \\ &= h_2^{-1} \left[z_1 + u_2 z_2 + \frac{(u_0 z_0) k_1^2}{u_0^2} \right] + h_2 w_1 + v_2, \end{aligned}$$

$$\begin{aligned} v'_1 &= (g_4 u'_1 + u'_0 + g_1)(s'_2/r) + v_1 \\ &= h_2^{-1} \left[z_0 + u_1 z_2 + u_2 z_1 + \frac{(u_2 z_0 + u_0 z_2)^2}{u_1 z_0 + u_0 z_1} \right] + (h_2 w_1)(f_6 + k_1) + v_1, \end{aligned}$$

$$\begin{aligned} v'_0 &= (g_4 u'_0 + g_0)(s'_2/r) + v_0 \\ &= h_2^{-1} \left[u_2 z_0 + u_1 z_1 + u_0 z_2 + \frac{(u_0 z_0) k_2^2}{u_0^2} \right] + (h_2 k_1)(k_1 + f_6 w_1) + v_0. \end{aligned}$$

And since $f + hv + v^2 = uz + u^2(x + f_6)$ we also have that

$$\begin{aligned} f_0 + v_0^2 &= u_0 z_0 + f_6 u_0^2, \\ f_1 &= u_1 z_0 + u_0 z_1 + u_0^2, \\ h_2 v_0 &= u_2 z_0 + u_1 z_1 + u_0 z_2 + f_6 u_1^2, \\ h_2 v_1 &= z_0 + u_2 z_1 + u_1 z_2 + u_1^2, \\ f_4 + h_2 v_2 + v_2^2 &= z_1 + u_2 z_2 + f_6 u_2^2, \\ 0 &= u_2^2 + z_2. \end{aligned}$$

We use the equations above to calculate k_1, k_2, w_1 and v'_3, v'_2, v'_1, v'_0 cheaper:

$$\begin{aligned} k_1 &= \frac{f_0 + v_0^2 + f_6 u_0^2}{f_1 + u_0^2}, k_2 = \frac{u_0(h_2 v_0 + u_1 z_1 + f_6 u_1^2)}{f_1 + u_0^2}, w_1 = \frac{u_0^2}{f_1 + u_0^2}, \\ v'_3 &= h_2^{-1} \left[z_2 + \frac{(f_0 + v_0^2 + f_6 u_0^2)^2}{u_0^2(f_1 + u_0^2)} \right], \\ v'_2 &= h_2^{-1} \left[f_4 + v_2^2 + f_6 u_2^2 + \frac{(f_0 + v_0^2 + f_6 u_0^2) k_1^2}{u_0^2} \right] + \frac{h_2 u_0^2}{f_1 + u_0^2}, \\ v'_1 &= h_2^{-1} \left[u_1^2 + \frac{(u_1 z_1 + f_6 u_1^2 + h_2 v_0)^2}{f_1 + u_0^2} \right] + \frac{h_2 u_0^2 (f_6 + k_1)}{f_1 + u_0^2}, \\ v'_0 &= h_2^{-1} \left[f_6 u_1^2 + \frac{(f_0 + v_0^2 + f_6 u_0^2) k_2^2}{u_0^2} \right] + (h_2 k_1) \left(k_1 + \frac{u_0^2 f_6}{f_1 + u_0^2} \right). \end{aligned}$$

We note that $rs'_2 = u_0^2(u_1 z_0 + u_0 z_1)h_2^5 = u_0^2(f_1 + u_0^2)h_2^5$, so it is very cheap to calculate rs'_2 since we do not need to know the exact coefficients of z . We describe the doubling formula for this case in Table 3. The operations are counted for the case $h_2 = 1, h_2^{-1}$ is 'small' (multiplication with h_2^{-1} are not counted), and arbitrary h_2 . Both h_2^2 and h_2^{-1} are precomputed.

Table 3. Doubling deg $h = 2$, $h_1 = 0$, deg $u = 3$

Step	Expression	$h_2 = 1$	h_2^{-1} small	h_2 arbitrary
Input $[u, v]$, $u = x^3 + u_2x^2 + u_1x + u_0$, $v = v_2x^2 + v_1x + v_0$; h_2^2, h_2^{-1} Output $[u'', v''] = 2[u, v]$				
1	Precomputation: $\tilde{u}_2 = u_2^2, \tilde{u}_1 = u_1^2, \tilde{u}_0 = u_0^2, z_2 = f_4 + v_2^2 + f_6\tilde{u}_2$; $z_1 = z_2 + h_2v_2 + \tilde{u}_2u_2, t_1 = f_0 + v_0^2 + f_6\tilde{u}_0$; $t_2 = f_6\tilde{u}_1, t_3 = t_2 + h_2v_0 + u_1z_1, t_4 = f_1 + \tilde{u}_0$; If $t_4 = 0$ then call the Cantor algorithm	5M, 5S	7M, 5S	7M, 5S
2	Compute s_1, s_0 : $t_5 = (t_4\tilde{u}_0)^{-1}, t_6 = t_4t_5, t_7 = \tilde{u}_0t_5$; $t_8 = t_1t_6, k_1 = t_1t_7, \tilde{k}_2 = t_3t_7$; $k_2 = u_0\tilde{k}_2, s_1 = u_2 + k_1, s_0 = u_1 + k_2$;	1I, 7M	1I, 7M	1I, 7M
3	Compute $u' = x^4 + u_3'x^3 + u_2'x^2 + u_1'x + u_0'$: $w_1 = \tilde{u}_0t_7, w_2 = h_2^2w_1, u_2' = s_1^2, u_1' = w_2(1 + w_1)$;	1M, 2S	3M, 1S	3M, 1S
4	Compute $v' = v_3'x^3 + v_2'x^2 + v_1'x + v_0'$: $v_3' = h_2^{-1}(\tilde{u}_2 + t_1^2t_5), v_2' = h_2^{-1}(z_2 + t_8k_1^2) + h_2w_1$; $v_1' = h_2^{-1}(\tilde{u}_1 + \tilde{k}_2t_3) + (h_2w_1)(f_6 + k_1)$; $v_0' = h_2^{-1}(t_2 + t_8k_2^2) + (h_2k_1)(k_1 + f_6w_1)$;	7M, 3S	9M, 3S	13M, 3S
5	Reduce u' , i.e. $u'' = x^3 + u_2''x^2 + u_1''x + u_0''$: $u_2'' = f_6 + v_3'^2, u_1'' = u_2' + h_2v_3'$; $u_0'' = f_4 + u_2'u_2' + u_1' + v_2'^2 + h_2v_2'$;	1M, 2S	3M, 1S	3M, 1S
6	Compute $v'' = v_2''x^2 + v_1''x + v_0''$: $v_2'' = v_2' + v_3'u_2'' + h_2, v_1'' = v_1' + v_3'u_1''$; $v_0'' = v_0' + v_3'u_0''$;	3M	3M	3M
Sum		1I, 24M, 12S	1I, 32M, 10S	1I, 36M, 10S

Remark 3. For general case with $h(x) = h_2x^2 + h_1x + h_0$, the authors in [GKP04] use a birational transformation to make the curve's coefficient f_6 zero. Their algorithm needs 1I, 52M, 8S to compute divisor class doubling. Using special curves with $h(x) = h_2x^2 + h_0$, our explicit formula requires only 1I, 24M, 12S for $h_2 = 1$. In the formulae presented in Table 3 there are four counted multiplications with f_6 which are cheaper when f_6 is 'small'.

7 Case deg $h = 3$

When h is of degree three, we cannot also make any of its coefficients zero in general. We will show that special curves with $h_2 = h_1 = h_0 = 0$ can obtain excellent performance in this section. We can construct a change of coordinates to make $f_5 = f_4 = f_3 = 0$ and $h_3 = 1$. The isomorphic curve is obtained by using the following birational transformation of variables and dividing the equation by h_3^{14} :

$$Y \leftarrow h_3^7 \tilde{Y} + h_3^3 f_5 \tilde{X}^2 + \frac{f_4 h_3^2 + f_5^2}{h_3} \tilde{X} + \frac{f_3}{h_3}, X \leftarrow h_3^2 \tilde{X}$$

Hence we obtain a curve of the form $Y^2 + X^3Y = X^7 + f_6X^6 + f_2X^2 + f_1X + f_0$. Adding a cubic factor to the substitution of \tilde{Y} one can achieve $f_6 = 0$ with probability 1/2. Thereby, there are only three free parameters f_2, f_1, f_0 .

Then the expressions for r and s will simplify to:

$$\begin{aligned} r &= u_0^3, s_2' = u_0(u_2z_0 + u_1z_1 + u_0z_2) + u_1^2z_0, \\ s_1' &= u_2[u_0(u_2z_0 + u_1z_1 + u_0z_2)] + u_0(u_1z_0 + u_0z_1), \\ s_0' &= u_1[u_0(u_2z_0 + u_1z_1 + u_0z_2)] + u_0[u_2(u_1z_0 + u_0z_1) + u_0z_0], \\ s_1 &= \frac{s_1'}{s_2'} = u_2 + k_1, s_0 = \frac{s_0'}{s_2'} = u_1 + k_2, \end{aligned}$$

where $k_1 = \frac{u_0(u_1z_0 + u_0z_1)}{u_0(u_2z_0 + u_1z_1 + u_0z_2) + u_1^2z_0}$ and $k_2 = \frac{u_0[u_2(u_1z_0 + u_0z_1) + u_0z_0]}{u_0(u_2z_0 + u_1z_1 + u_0z_2) + u_1^2z_0}$. In this case, we have that

$$\begin{aligned} u_3' &= 0, u_2' = s_1^2 + \frac{r}{s_2'}, u_1' = \frac{r}{s_2'}(k_1 + \frac{r}{s_2'}), u_0' = \frac{r}{s_2'}(k_2 + u_2k_1 + \frac{rf_6}{s_2'}) + s_0^2, \\ v_3' &= (u_2' + g_3)(s_2'/r) + 1 = \frac{u_0z_0}{u_0^2} + \frac{(u_1z_0 + u_0z_1)^2}{u_0^2(u_2z_0 + u_1z_1 + u_0z_2) + u_1^2(u_0z_0)}, \\ v_2' &= (g_4u_2' + u_1' + g_2)(s_2'/r) + v_2 = \frac{(u_1z_0 + u_0z_1)(u_2' + u_2^2)}{u_0^2} + z_2 + k_1 + \frac{r}{s_2'} + v_2, \\ v_1' &= (g_4u_1' + u_0' + g_1)(s_2'/r) + v_1 = \frac{k_2[u_2(u_1z_0 + u_0z_1) + u_0z_0] + u_2^2(u_0z_0)}{u_0^2} + \\ &\quad k_1(k_1 + \frac{r}{s_2'}) + (k_2 + u_2k_1 + \frac{rf_6}{s_2'}) + (z_1 + u_2z_2) + v_1, \\ v_0' &= (g_4u_0' + g_0)(s_2'/r) + v_0 = \frac{(u_1z_0 + u_0z_1)(u_0' + u_1^2)}{u_0^2} + (z_0 + u_2z_1 + u_1z_2) + v_0. \end{aligned}$$

And since $f + hv + v^2 = uz + u^2(x + f_6)$ we also have that

$$\begin{aligned} f_0 + v_0^2 &= u_0z_0 + f_6u_0^2, \\ f_1 &= u_1z_0 + u_0z_1 + u_0^2, \\ f_2 + v_1^2 &= u_2z_0 + u_1z_1 + u_0z_2 + f_6u_1^2, \\ v_0 &= z_0 + u_2z_1 + u_1z_2 + u_1^2, \\ v_1 + v_2^2 &= z_1 + u_2z_2 + f_6u_2^2, \\ v_2 &= u_2^2 + z_2. \end{aligned}$$

Using the equations above, we can calculate $k_1, k_2, \frac{r}{s_2'}$ and v_3', v_2', v_1', v_0' cheaper:

$$k_1 = \frac{u_0^2(f_1 + u_0^2)}{u_0^2(f_2 + v_1^2 + f_6u_1^2) + u_1^2(f_0 + v_0^2 + f_6u_0^2)},$$

$$\begin{aligned}
 k_2 &= \frac{u_0^2[u_2(f_1 + u_0^2) + (f_0 + v_0^2 + f_6u_0^2)]}{u_0^2(f_2 + v_1^2 + f_6u_1^2) + u_1^2(f_0 + v_0^2 + f_6u_0^2)}, \\
 \frac{r}{s_2} &= \frac{u_0^4}{u_0^2(f_2 + v_1^2 + f_6u_1^2) + u_1^2(f_0 + v_0^2 + f_6u_0^2)}, \\
 v_3' &= \frac{f_0 + v_0^2 + f_6u_0^2}{u_0^2} + \frac{(f_1 + u_0^2)^2}{u_0^2(f_2 + v_1^2 + f_6u_1^2) + u_1^2(f_0 + v_0^2 + f_6u_0^2)}, \\
 v_2' &= \frac{(f_1 + u_0^2)(u_2' + u_2^2)}{u_0^2} + k_1 + \frac{r}{s_2} + u_2^2, \\
 v_1' &= \frac{k_2[u_2(f_1 + u_0^2) + (f_0 + v_0^2 + f_6u_0^2)] + u_2^2(f_0 + v_0^2 + f_6u_0^2)}{u_0^2} + \\
 &\quad k_1(k_1 + \frac{r}{s_2}) + (k_2 + u_2k_1 + \frac{rf_6}{s_2}) + (v_2^2 + f_6u_2^2), \\
 v_0' &= \frac{(f_1 + u_0^2)(u_0' + u_1^2)}{u_0^2} + u_1^2.
 \end{aligned}$$

We note that $rs_2' = u_0^2[u_0^2(u_2z_0 + u_1z_1 + u_0z_2) + u_1^2(u_0z_0)] = u_0^2[u_0^2(f_2 + v_1^2 + f_6u_1^2) + u_1^2(f_0 + v_0^2 + f_6u_0^2)]$, so we can calculate rs_2' cheaply without knowing the exact coefficients of z . We present the explicit formula for this case in Table 4.

Table 4. Doubling deg $h = 3$, $h_2 = h_1 = h_0 = 0$, deg $u = 3$

Input	$[u, v], u = x^3 + u_2x^2 + u_1x + u_0, v = v_2x^2 + v_1x + v_0;$	
Output	$[u'', v''] = 2[u, v]$	
Step	Expression	Cost
1	Precomputation: $\tilde{u}_2 = u_2^2, \tilde{u}_1 = u_1^2, \tilde{u}_0 = u_0^2, \tilde{v}_2 = v_2^2, \tilde{v}_1 = v_1^2, \tilde{v}_0 = v_0^2, t_1 = f_0 + \tilde{v}_0 + f_6\tilde{u}_0;$ $t_2 = f_2 + \tilde{v}_1 + f_6\tilde{u}_1, t_3 = \tilde{u}_0t_2 + \tilde{u}_1t_1, t_4 = f_1 + \tilde{u}_0, t_5 = u_2t_4 + t_1;$ If $t_3 = 0$ then call the Cantor algorithm	5M, 6S
2	Compute s_1, s_0 : $t_6 = (t_3\tilde{u}_0)^{-1}, t_7 = t_3t_6, t_8 = \tilde{u}_0t_6, t_9 = \tilde{u}_0t_8;$ $k_1 = t_4t_9, k_2 = t_5t_9, s_1 = u_2 + k_1, s_0 = u_1 + k_2;$	1I, 6M
3	Compute $u' = x^4 + u_3'x^3 + u_2'x^2 + u_1'x + u_0'$: $w_4 = \tilde{u}_0t_9, u_2' = s_1^2 + w_4, t_{10} = k_1 + w_4, u_1' = w_4t_{10};$ $t_{11} = k_2 + u_2k_1 + f_6w_4, u_0' = s_0^2 + w_4t_{11};$	5M, 2S
4	Compute $v' = v_3x^3 + v_2x^2 + v_1x + v_0'$: $v_3' = t_1t_7 + t_4^2t_8, t_{12} = t_4t_7, v_2' = t_{12}(u_2' + \tilde{u}_2) + k_1 + w_4 + \tilde{u}_2;$ $v_1' = k_1t_{10} + t_{11} + (k_2t_5 + \tilde{u}_2t_1)t_7 + \tilde{v}_2 + f_6\tilde{u}_2, v_0' = t_{12}(u_0' + \tilde{u}_1) + \tilde{u}_1;$	10M, 1S
5	Reduce u' , i.e. $u'' = x^3 + u_2''x^2 + u_1''x + u_0''$: $u_2'' = f_6 + v_3' + v_3'^2, u_1'' = u_2' + v_2', u_0'' = u_2'u_2' + u_1' + v_2'^2 + v_1';$	1M, 2S
6	Compute $v'' = v_2''x^2 + v_1''x + v_0''$: $v_2'' = v_2' + (v_3' + 1)u_2'', v_1'' = v_1' + (v_3' + 1)u_1'', v_0'' = v_0' + (v_3' + 1)u_0'';$	3M
Sum		1I, 30M, 11S

Remark 4. In [GKP04], the authors discuss two types of curves with $h_2 = 0$ and $f_6 = 0$, respectively. Their doubling formulae cost $1I, 63M, 9S$ and $1I, 64M, 5S$ for these two different cases. We note that using special curves with $h(x) = h_3x^3$ can lead to fast computation of a divisor class doubling. We derive the new explicit doubling formula which needs only $1I, 30M, 11S$. In addition, there are four counted multiplications with f_6 which can be computed cheaply when f_6 is 'small' in the formulae.

8 Summary

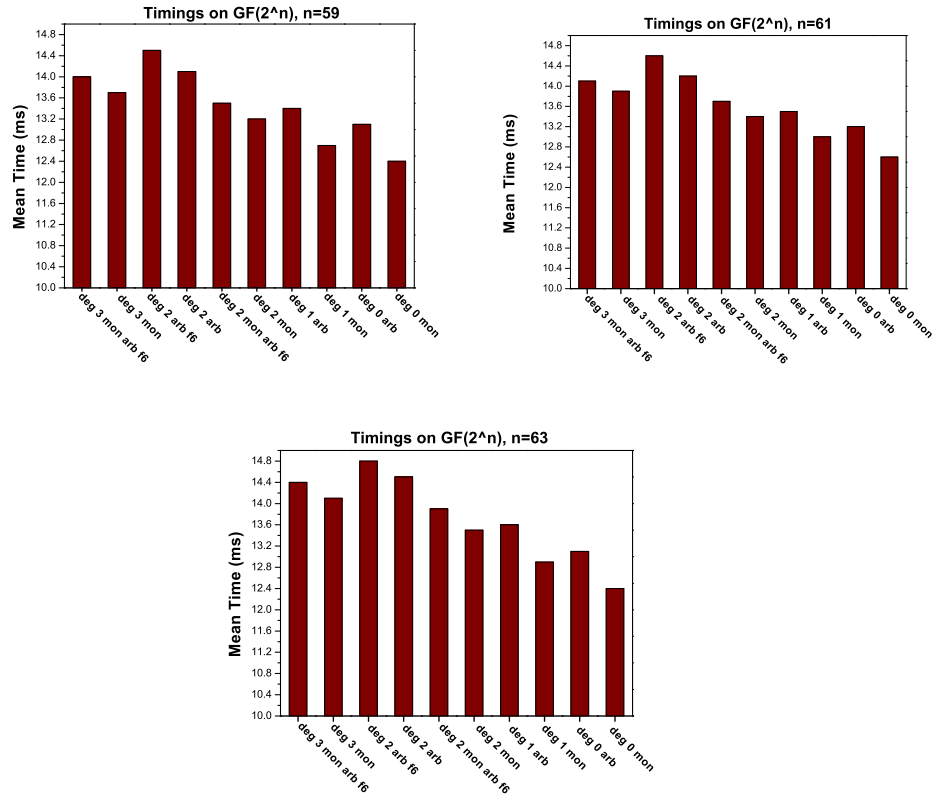
Depending on the degree of h , we derived the corresponding explicit formulae which can compute doublings fast in the previous sections. For h of degree 0 and 1 the case f_6 not small does not apply since we make it zero by isomorphic transformations. We also find fast doubling formulae for special curves when the degree of h is 2 and 3. All results are summarized in Table 5.

Table 5. Overview

$h(x)$	$h(x) = h_0$		
h_i	$h_0 = 1$	h_0^{-1} small	h_0 arb.
cost	$1I, 11M, 11S$	$1I, 13M, 11S$	$1I, 17M, 11S$
$h(x)$	$h(x) = h_1x$		
h_i	$h_1 = 1$	h_1^{-1} small	h_1 arb.
cost	$1I, 13M, 13S$	$1I, 16M, 12S$	$1I, 20M, 12S$
$h(x)$	$h(x) = h_2x^2$		
h_i	$h_2 = 1$	h_2^{-1} small	h_2 arb.
f_6 small	$1I, 20M, 12S$	$1I, 28M, 10S$	$1I, 32M, 10S$
f_6 arb.	$1I, 24M, 12S$	$1I, 32M, 10S$	$1I, 36M, 10S$
$h(x)$	$h(x) = x^3$		
f_6 small	$1I, 26M, 11S$		
f_6 arb.	$1I, 30M, 11S$		

9 Experimental Results

In order to test the performance of our new doubling formulae, we implemented genus 3 HECC over three binary fields. Due to the attack proposed by Thériault [Thé03], we should select at least 56-bit finite fields in order to obtain the same security as a 160-bit elliptic curve cryptosystem. We used the binary fields $GF(2^{59})$, $GF(2^{61})$ and $GF(2^{63})$. For $GF(2^{59})$ and $GF(2^{61})$, we used the minimal weight irreducible pentanomial $x^{59} + x^7 + x^4 + x^2 + 1$ and $x^{61} + x^5 + x^2 + x + 1$ to construct finite fields, respectively. However, for $GF(2^{63})$, we used the minimal weight irreducible trinomial $x^{63} + x + 1$ as field extension. Efficient algorithms summarized in [Pel02] were used to perform the field arithmetic. In addition, We used a NAF method to perform the scalar multiplication. All tests are implemented on a Pentium-M @1.5 GHz processor and with C programming language.



The experimental results were depicted in the following three bar graphs. In the graphs above we include the following ten cases respectively:

- deg 3 mon arb f_6 : The case where $\deg h = 3, h_2 = h_1 = h_0 = 0, f_6 \neq 0$ and $h_3 = 1$;
- deg 3 mon: The case where $\deg h = 3, h_2 = h_1 = h_0 = 0, f_6 = 0$ and $h_3 = 1$;
- deg 2 arb f_6 : The case where $\deg h = 2, h_1 = h_0 = 0, f_6 \neq 0$;
- deg 2 arb: The case where $\deg h = 2, h_1 = h_0 = 0, f_6 = 0$;
- deg 2 mon arb f_6 : The case where $\deg h = 2, h_1 = h_0 = 0, f_6 \neq 0$ and $h_2 = 1$;
- deg 2 mon: The case where $\deg h = 2, h_1 = h_0 = 0, f_6 = 0$ and $h_2 = 1$;
- deg 1 arb: The case where $\deg h = 1, h_0 = 0$;
- deg 1 mon: The case where $\deg h = 1, h_0 = 0$ and $h_1 = 1$;
- deg 0 arb: The case where $\deg h = 0$;
- deg 0 mon: The case where $\deg h = 0$ and $h_0 = 1$;

10 Conclusion and Outlook

We have discussed how to accelerate the computation of divisor class doublings for genus 3 hyperelliptic curves defined over binary fields and given explicit formulae for four special types of curves. Compared with the results in [PWGP03,GKP04], our explicit formulae have reduced some field operations further and shown excellent performance on a Pentium-M processor. The divisor addition formulae depend far less on the coefficients of h . In [GKP04], the authors have improved the corresponding addition explicit formulae according to the degree of h .

In this paper we restricted our attentions to affine coordinate system. However, the authors of this paper have obtained inversion-free explicit formulae for genus 3 hyperelliptic curves [FWW05]. For genus 3 HECC defined over binary fields, the authors gave only inversion-free explicit formulae for special curves with $h(x) = 1$. Hence, how to extended the idea of this paper to projective coordinate system and improve the formulae in [FWW05] will be the next logical step to accelerate the implementation for genus 3 HECC.

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